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Issues in Crater Studies and the Dating of Planetary Surfaces

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SCHOOL OF PROFESSIONAL STUDIES

22 May 2015

Spatial Statistics



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Presentation Outline

- Introduction
- Impacts
- Secondary Impacts
- CSFD Method
- NND Method
- Grouping Methods
- Spatial Correlation Methods
- Summary
- Conclusions



Cratering process assumptions

- 1 Craters form stochastically through time
- 2 Craters form randomly (mostly) across a surface
- 3 Impact cratering is an ongoing process
- Two cratering processes tied to stochastic assumptions
 - Secondary cratering
 - 2 Crater saturation
- Spatial statistics to identify secondaries and saturation

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- 1 Familiar methods
- 2 Esoteric methods



- Secondary cratering
 - Secondaries exhibit non-random patterns assumption 2 violation
 - Task is identification of secondaries from spatial statistics
- Crater saturation
 - New craters compromise the structure of an existing crater
 - Crater spatial population distributions static in time and space assumption 3 violation

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Focus of this presentation is on secondary cratering

	Primaries	CSFD	NND		Conclusions
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Impacts	S				

Primary impacts

Complete spatial random (CSR) distributions (some deviation)

- CSR follows a Poisson probability distribution function (pdf)
- Poisson pdf is counts by area (univariate spatial density)
- Small crater impacts include
 - Primaries
 - Secondaries
 - Sesquinary secondaries (maybe)
- Primaries and sesquinary secondaries considered CSR
- Secondaries can cluster or appear as CSR

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Secondary Impacts: Morphology

- Near primaries tend to be unambiguous
- Distant more challenging to identify
- Sesquinary secondaries usually indistinguishable from primaries





- Left panel CSR
- Middle panel clusters
- Right panel regular (uniform)



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- Region divided and CSFDs compared
- CSFD slopes
- Nearest neighbor distance (NND) with Z-statistic

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- Univariate spatial density comparisons among region subdivisions
- Sub-region differences suggest secondary contamination
- Similarities suggest no contamination or CSR ambiguity
- Steeper CSFD slopes (than primary SFDs) suggest secondaries

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- Dependent on region characteristics
- Sensitive to CSFD uncertainties
- Specificity poor
- Spatial distribution identification challenging
- Spatial correlation ignored
- CSFD comparison and slope, may be improved using CEDF

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- Nearest Neighbor Distance (NND)
- Uses location (lat/lon), independent of region characteristics
- Under CSR, counts pdf transformed to univariate distance pdf

$$1 - \mathcal{P}(N = 0) = 1 - \frac{\rho \pi r^2}{0!} e^{-\rho \pi r^2}, \text{ NND} < r$$

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- Distances are Z-scores so standard deviations from CSR
 - $Z < 0 \Rightarrow$ clustering
 - $Z = 0 \Rightarrow CSR$
 - $Z > 0 \Rightarrow$ uniformity
 - Location uncertainty quantifiable



- Spatial correlation information lost
- Only smallest scale information, no information on all scales
- Only magnitude and direction of deviations from CSR
- Affected by boundaries, though mitigation possible

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- Cluster methods
- Ripley's K-function
- Besag's *L*-function
- Pair Correlation Function

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Cluster Analysis Methods

- Exploratory method for spatial data
- Groups craters by specified homogeneous properties
- Common techniques
 - Agglomerative hierarchy
 - K-means (K specified)
 - Categorical MLE (K estimated)
- Useful for visualizing spatial relationships
- Visualization of probability of a crater as a secondary



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Intensity function measure of counts / unit area:

$$\lambda = \frac{N}{|A|}$$
, (counts, N, for normalized area, $|A|$)

Implementations using λ (specified) or $\hat{\lambda}$ (estimated)

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- Ripley's K-function
- Besag's L-function
- Two point correlation function
- These methods identify
 - CSR
 - Regularity
 - Clustering

Introduction Primaries Secondaries CSFD NND Grouping **Spatial** Summary Conclusions

Ripley's *K*-Function: $K(r) \equiv \lambda^{-1}\mathcal{E}$ (# nonrandom events $0 \le r \le h$)

- Captures spatial areal dependence (correlation)
- Red dashed curve is CSR with 0.05 uncertainty region $K(r) = \pi r^2, r \ge 0$
- Black solid curve shows clustering at scales > 5° $K(r) > \pi r^2$ (dashed curve has boundary correction)
- If black curve below CSR region, distribution regular $K(r) < \pi r^2$



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K-Function for All



- K indepdent of region shape
- *K* has region boundary accountability
- Information exists on all scales
- Accounts for lat/lon uncertainties
- Accounts for spatial correlation

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Besag's *L*-function: $L(r) = \sqrt{K(r)/\pi} - r, r \ge 0$

- Function of Ripley's K, has same information
- Plot easier to interpret than K-function
- Zero-line and uncertainty represents CSR
- Excursions above the zero-line imply clustering > 5°
- Excursions below the zero-line imply regularity



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L-Function for All

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- Adapted to address clustering interactions
 Two or more populations, e.g., same-sized craters of primaries and secondaries
- Counts of 1 population assessed around counts of another population
 - > 0 segregated
 - < 0 aggregated</p>
 - = 0 no interaction
- Can help identify types in mixes of same-size primaries and secondaries

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Pair Correlation Function

- Counts events in annuli rather than circles about a reference
- Related to the differential of Ripley's K-function
- Derives from the joint probability 2 events lie in infinitesimal annuli of areas dA₁ and dA₂ giving the correlation ξ(r)

$$\xi(r) = \frac{\lambda(r)}{\bar{\rho}^2} - 1$$



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PCF for All



- Clustering methods for
 - Data exploration
 - Spatial dependence visualization
- Pair correlation function
 - Contains the same information as K- and L-functions
 - Requires binning, hence less desireable

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K- and L-functions

- Like CEDF, not binnied
- Unbaised estimation of spatial correlation
- Spatial correlations at all scales

Lattice spatial methods

- Independent of lat/lon
- Utilizes 2-D NND techniques that include spatial correlation

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Untried? for secondary crater identification



- Existing implementations of spatial methods
 - Alone will not discriminate unambiguously whether a crater is a secondary
 - Mathematics can be reformulated to assign a probability a crater is a secondary
 - Mathematics can be reformulated to assign a crater as a secondary with specified uncertainty

Image: Image:

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